

QUANTUM MECHANICS EXAM

18 January 2021

Answers sheet

We consider a one-dimensional system that is in a state whose wave function is given by

$$\psi(x) = \langle x|\psi\rangle = Ne^{-\frac{\sigma}{2}x^2} (e^{ik_0x} + e^{-ik_0x}) = 2Ne^{-\frac{\sigma}{2}x^2} \cos(k_0x), \quad (1)$$

where N is a normalization constant

$$N = \left(2\sqrt{\frac{\pi}{\sigma}} \left(1 + e^{-k_0^2/\sigma}\right)\right)^{-1/2}. \quad (2)$$

(1) For the expectation value of x we find

$$\langle x\rangle = \int_{-\infty}^{\infty} dx \psi^*(x) x \psi(x) = 0, \quad (3)$$

because $\psi(x)$ is symmetric while x is anti-symmetric. Now for the expectation value of p we find

$$\langle p\rangle = \int_{-\infty}^{\infty} dx \psi^*(x) (-i\hbar) \frac{\partial \psi(x)}{\partial x} = 0, \quad (4)$$

where the integrand is also anti-symmetric.

(2) The probability distribution $\rho(x)$ for a measurement of position is

$$\rho(x) = |\psi(x)|^2 = 4N^2 e^{-\sigma x^2} \cos^2(k_0x). \quad (5)$$

(3) The momentum wave function is found by calculating the Fourier transform of the position wave function:

$$\psi(k) = \int \frac{dx}{\sqrt{2\pi}} e^{ikx} \psi(x), \quad (6)$$

$$= \int \frac{dx}{\sqrt{2\pi}} N e^{\frac{\sigma}{2}x^2} (e^{i(k-k_0)x} + e^{-i(k+k_0)x}), \quad (7)$$

$$= \int \frac{dx}{\sqrt{2\pi}} N \left(e^{-\frac{\sigma}{2}(x+i\frac{1}{\sigma}(k-k_0))^2} e^{\frac{1}{\sigma}(k-k_0)^2} + e^{-\frac{\sigma}{2}(x+i\frac{1}{\sigma}(k+k_0))^2} e^{\frac{1}{2\sigma}(k+k_0)^2} \right), \quad (8)$$

$$= \frac{N}{\sqrt{\sigma}} \left(e^{-(k-k_0)^2/2\sigma} + e^{-(k+k_0)^2/2\sigma} \right), \quad (9)$$

where in the step from the third to the last line the Gaussian integral was performed for each of the two terms.

(4) The probability distribution $\rho(k)$ for a measurement of momentum is

$$\rho(k) = |\psi(k)|^2 = \frac{N^2}{\sigma} \left(e^{-(k-k_0)^2/\sigma} + e^{-(k+k_0)^2/\sigma} + 2e^{-(k^2+k_0^2)/\sigma} \right). \quad (10)$$

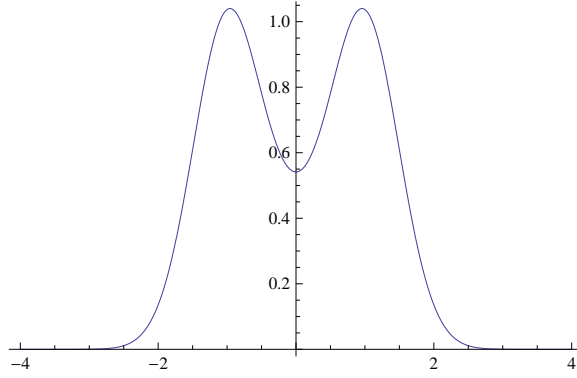


Figure 1: Qualitative shape of the momentum probability distribution $\rho(k)$ (the scale on the axes is arbitrary).

- (5) The qualitative shape of the momentum probability distribution is shown in Fig. 1: it is a superposition of two Gaussians centered in $\pm k_0$ respectively. Therefore, the most probable values of a measurement of momentum are at $k = \pm k_0$. The wave function Eq. (1) is a superposition of two eigenfunctions ψ_{\pm} ,

$$\psi_{\pm}(x) = N e^{-\frac{\sigma}{2}x^2} e^{\pm ik_0 x}. \quad (11)$$

These eigenfunctions correspond to two wave packets, both centered in the origin in position space, but moving in opposite directions along the x -axis, so centered about two opposite values $k = \pm k_0$ in momentum space.

- (6) To find the expectation value of the energy, we have to evaluate $\langle H \rangle$.

Starting with (a)

$$\langle H \rangle = \left\langle \frac{p^2}{2m} \right\rangle = \frac{\hbar^2}{2m} \langle k^2 \rangle. \quad (12)$$

The simplest way of computing the integral is to use momentum space, in which case we get

$$\langle k^2 \rangle = \int_{-\infty}^{\infty} k^2 |\psi(k)|^2 dk \quad (13)$$

$$= \int_{-\infty}^{\infty} k^2 \rho(k) dk \quad (14)$$

where $\psi(k)$ is the momentum-space wave function Eq. (6) determined at point 3 and $\rho(k)$ is the momentum probability distribution Eq. (10) determined at point 4. All the integrals are of the form of the integrals found when computing the uncertainty in a wave packet. The result is

$$\langle H \rangle = \frac{\hbar^2}{2m} \langle k^2 \rangle = \frac{\hbar^2}{2m} \left(\frac{\sigma}{2} + \frac{k_0^2}{1 + e^{-k_0^2/\sigma}} \right). \quad (15)$$

For (b) we have

$$\langle H \rangle = \left\langle \frac{p^2}{2m} + \kappa x \right\rangle = \frac{\hbar^2}{2m} \langle k^2 \rangle + \kappa \langle x \rangle = \frac{\hbar^2}{2m} \langle k^2 \rangle, \quad (16)$$

where in the last step we have used Eq. (3). Therefore, the result is the same as for (a).

- (7) Wave packets of minimal uncertainty are those for which

$$\Delta^2 x \Delta^2 p = \frac{\hbar}{4}. \quad (17)$$

The necessary and sufficient condition for a wave packet to have minimal uncertainty is

$$(\hat{p} - \langle \hat{p} \rangle)|\psi\rangle = i\lambda(\hat{x} - \langle \hat{x} \rangle)|\psi\rangle, \quad (18)$$

where $\lambda \in \mathbb{R}$.

The condition on the wave function is found computing

$$\langle x | (\hat{p} - \langle \hat{p} \rangle) | \psi \rangle = \langle x | \hat{p} | \psi \rangle = -i\hbar \partial_x \psi(x) = -i\hbar \left(\sigma x \psi(x) - 2N e^{\frac{\sigma}{2} x^2} \sin(k_0 x) k_0 \right), \quad (19)$$

This is clearly not equal to the right hand side:

$$i\lambda \langle x | (\hat{x} - \langle \hat{x} \rangle) | \psi \rangle = i\lambda \langle x | \hat{x} | \psi \rangle = x\psi(x). \quad (20)$$

Above we used the results of exercise 1, where we found that $\langle x \rangle = 0$ and $\langle p \rangle = 0$.

This means that the state of Eq. (1) does not satisfy the condition to be a state of minimal uncertainty. This is because Eq. (1) is not a wave packet, but a superposition of two wave packets.

- (8) Assuming that the time-dependence is given by a free-particle Hamiltonian, the Heisenberg equations of motion for the operators x and p are

$$\frac{dx}{dt} = \frac{i}{\hbar} [H, x] = \frac{i}{\hbar} \frac{1}{2m} [p^2, x] = \frac{p}{m} \quad (21)$$

$$\frac{dp}{dt} = \frac{i}{\hbar} [H, p] = 0. \quad (22)$$

Using these equations we find that the time dependence of the position and momentum operators is

$$p(t) = p(0), \quad (23)$$

$$x(t) = x(0) + \frac{p(0)}{m} t. \quad (24)$$

The time dependence of the expectation values is then found to be

$$\langle p(t) \rangle = \langle p(0) \rangle = 0, \quad (25)$$

$$\langle x(t) \rangle = \langle x(0) + \frac{p(0)}{m} t \rangle = 0, \quad (26)$$

where we made use of the fact that $\langle p(0) \rangle = \langle x(0) \rangle = 0$, which are the results of exercise (1). Because time evolution is unitary, these results hold for all times.

- (9) Before performing the measurement, the time evolution is the same as in the previous point, so for $t < 0$ Eqs. (25-26) are still true.

Upon performing the measurement, one finds a value for the momentum k with a probability given by Eq. (10). After this measurement, the wave function is a plane wave with momentum $p = \hbar k_m$, where k_m is the measured value.

Hence for $t > 0$ one has

$$\langle p(t) \rangle = k_m, \quad (27)$$

$$\langle x(t) \rangle = \langle x(0) + \frac{p(0)}{m} t \rangle = \langle x(0) + \frac{\hbar k_m}{m} t \rangle, \quad (28)$$

where the mean value of position must be computed in a plane wave. In this state, the expectation value vanishes, but the uncertainty is infinite. So for all $t > 0$ the expectation value of position is ill-defined (indeterminate). (The answer found using $\langle x(t) \rangle = 0$ is also considered to be correct).

- (10) For a free particle the Hamiltonian is $H = p^2/2m$, with $p = \hbar k$. The time dependent wave function in momentum space is

$$\psi(k, t) = \langle k | \psi, t \rangle = \langle k | e^{-iHt/\hbar} | \psi \rangle = e^{-ik^2\hbar t/(2m)} \psi(k), \quad (29)$$

where $\psi(k)$ has been calculated in exercise 3. The time dependent wave function is used to determine the probability distribution of momentum at time t :

$$\rho(k, t) = |\psi(k, t)|^2 = |e^{-ik^2\hbar t/(2m)} \psi(k)|^2 = |\psi(k)|^2 = \frac{N^2}{\sigma} \left(e^{-(k-k_0)^2/\sigma} + e^{-(k+k_0)^2/\sigma} + 2e^{-(k^2+k_0^2)/\sigma} \right). \quad (30)$$

The result does not depend on time because momentum eigenstates the Hamiltonian is translationally invariant and momentum is conserved. Equivalently, momentum eigenstates are also energy eigenstates.

- (11) In the limit $\sigma \rightarrow 0$, the probability distribution reduces to two Dirac Delta functions located at $k = \pm k_0$ (see Fig 4.1 and Eq. (4.23) of the textbook).

$$\lim_{\sigma \rightarrow 0} \rho(k, t) = \frac{1}{2} (\delta(k + k_0) + \delta(k - k_0)) \quad (31)$$